# Curvature-free estimates for solutions of variational problems in Riemannian geometry

Alexander Nabutovsky

Department of Mathematics, University of Toronto

November 9, 2014

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <



#### Theorem

(A. Fet - L. Lyusternik) Let M be a closed Riemannian manifold. There exists at least one non-trivial periodic geodesic on M.

#### Theorem

(A. Fet - L. Lyusternik) Let M be a closed Riemannian manifold. There exists at least one non-trivial periodic geodesic on M.

Let *I* denote the minimal length of a non-trivial periodic geodesic. Problem (M. Gromov): Is there a constant c(n) depending only on the dimension *n* of *M* such that  $l \leq c(n)vol(M^n)^{\frac{1}{n}}$ ?

#### Theorem

(A. Fet - L. Lyusternik) Let M be a closed Riemannian manifold. There exists at least one non-trivial periodic geodesic on M.

Let *I* denote the minimal length of a non-trivial periodic geodesic. Problem (M. Gromov): Is there a constant c(n) depending only on the dimension *n* of *M* such that  $l \le c(n)vol(M^n)^{\frac{1}{n}}$ ? Problem: Is there a constant C(n) such that

 $I \leq C(n)$  diameter(M)?

#### Theorem

(J.-P. Serre) Let M be a closed Riemannian manifold, p, q a pair of points on M. There exists infinitely many geodesics connecting p and q.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

#### Theorem

(J.-P. Serre) Let M be a closed Riemannian manifold, p, q a pair of points on M. There exists infinitely many geodesics connecting p and q.

Note that p and q can be the same point. In this case geodesics connecting p and q become geodesic loops based at p.

#### Theorem

(J.-P. Serre) Let M be a closed Riemannian manifold, p, q a pair of points on M. There exists infinitely many geodesics connecting p and q.

Note that p and q can be the same point. In this case geodesics connecting p and q become geodesic loops based at p. Question. Can we majorize lengths of the m shortest geodesics connecting p and q in terms of m, the dimension and the diameter of M?

#### Theorem

(J.-P. Serre) Let M be a closed Riemannian manifold, p, q a pair of points on M. There exists infinitely many geodesics connecting p and q.

Note that p and q can be the same point. In this case geodesics connecting p and q become geodesic loops based at p. Question. Can we majorize lengths of the m shortest geodesics connecting p and q in terms of m, the dimension and the diameter of M?

#### Theorem

(L. Lyusternik-A. Shnirelman) Let M be a Riemannian 2-sphere. There exists at least three distinct simple periodic geodesics on M.

#### Theorem

(J.-P. Serre) Let M be a closed Riemannian manifold, p, q a pair of points on M. There exists infinitely many geodesics connecting p and q.

Note that p and q can be the same point. In this case geodesics connecting p and q become geodesic loops based at p. Question. Can we majorize lengths of the m shortest geodesics connecting p and q in terms of m, the dimension and the diameter of M?

#### Theorem

(L. Lyusternik-A. Shnirelman) Let M be a Riemannian 2-sphere. There exists at least three distinct simple periodic geodesics on M.

Question: Can we majorize their lengths in terms of the diameter of M?

#### Theorem

(F. Almgren-J. Pitts) Let M be a closed Riemannian manifold of dimension  $n \in \{3, 4, 5, 6, 7\}$ . Then there exists an embedded smooth minimal hypersurface in M.

This result can be generalized to other dimensions and codimensions if one does not insist on the smoothness of the minimal object anymore.

1. Some quantitative versions of Fet-Lyusternik theorem.

## 1. Some quantitative versions of Fet-Lyusternik theorem.

*I* denotes the length of a shortest non-constant periodic geodesic. An obvious observation: If *M* is nonsimply-connected, then  $I \le 2d$ , (*d* denotes diameter of *M*) (Exercise).

## But

#### Theorem

(F. Balacheff, C. Croke, M. Katz) There exist Riemannian metrics arbitrarily close to the standard round metric on  $S^2$  such that l > 2d.

## But

#### Theorem

(F. Balacheff, C. Croke, M. Katz) There exist Riemannian metrics arbitrarily close to the standard round metric on  $S^2$  such that l > 2d.

#### Yet:

#### Theorem

(A.N. and R. Rotman; independently S. Sabourau) If M is diffeomorphic to  $S^2$ , then  $l \leq 4d$ .

This result improves the constant in earlier inequality  $l \leq 9d$  by C. Croke.

## But

#### Theorem

(F. Balacheff, C. Croke, M. Katz) There exist Riemannian metrics arbitrarily close to the standard round metric on  $S^2$  such that l > 2d.

#### Yet:

#### Theorem

(A.N. and R. Rotman; independently S. Sabourau) If M is diffeomorphic to  $S^2$ , then  $l \leq 4d$ .

This result improves the constant in earlier inequality  $l \leq 9d$  by C. Croke.

Problem. GUESS a Riemannian metric on  $S^2$  for which  $\frac{1}{d}$  is (nearly) maximal possible.

Also, if 
$$M = S^2$$
, then

#### Theorem

(R. Rotman)  $l \leq 4\sqrt{2}\sqrt{Area(M)}$ .

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Also, if  $M = S^2$ , then

#### Theorem

(R. Rotman)  $I \leq 4\sqrt{2}\sqrt{Area(M)}$ .

This result improves the constant 31 in an earlier similar inequality by C. Croke.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Also, if  $M = S^2$ , then

#### Theorem

(R. Rotman)  $I \leq 4\sqrt{2}\sqrt{Area(M)}$ .

This result improves the constant 31 in an earlier similar inequality by C. Croke.

Conjectured optimal shape (E.Calabi): Two equilateral triangles glued along their common boundary.

*I* and the volume of M: nonsimply-connected case. Systolic geometry: Find an upper bound for the length of the shortest non-contractible periodic geodesic on M in terms of vol(M).

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Systolic geometry: Find an upper bound for the length of the shortest non-contractible periodic geodesic on M in terms of vol(M).

Lowner, Pu, Accola, Blatter, Yu. Burago, Zalgaller, Gromov,

Bavard, Calabi, M. Katz, Buser, Sarnak, Sabourau...

Systolic geometry: Find an upper bound for the length of the shortest non-contractible periodic geodesic on M in terms of vol(M).

Lowner, Pu, Accola, Blatter, Yu. Burago, Zalgaller, Gromov, Bavard, Calabi, M. Katz, Buser, Sarnak, Sabourau...

A manifold  $M^n$  is called essential if the image of its fundamental homology class in homology of  $K(\pi_1(M^n), 1)$  is non-trivial (under the homomorphism induced by the classifying map).

Systolic geometry: Find an upper bound for the length of the shortest non-contractible periodic geodesic on M in terms of vol(M).

Lowner, Pu, Accola, Blatter, Yu. Burago, Zalgaller, Gromov, Bavard, Calabi, M. Katz, Buser, Sarnak, Sabourau...

A manifold  $M^n$  is called essential if the image of its fundamental homology class in homology of  $K(\pi_1(M^n), 1)$  is non-trivial (under the homomorphism induced by the classifying map). Essential manifolds include non-simply connected surfaces, tori,  $RP^n$ .

Systolic geometry: Find an upper bound for the length of the shortest non-contractible periodic geodesic on M in terms of vol(M).

Lowner, Pu, Accola, Blatter, Yu. Burago, Zalgaller, Gromov, Bavard, Calabi, M. Katz, Buser, Sarnak, Sabourau...

A manifold  $M^n$  is called essential if the image of its fundamental homology class in homology of  $K(\pi_1(M^n), 1)$  is non-trivial (under the homomorphism induced by the classifying map). Essential manifolds include non-simply connected surfaces, tori,  $RP^n$ .

#### Theorem

(*M.* Gromov) If  $M^n$  is essential, then there exists a non-contractible periodic geodesic of length  $\leq c(n)vol(M^n)^{\frac{1}{n}}$ .

Systolic geometry: Find an upper bound for the length of the shortest non-contractible periodic geodesic on M in terms of vol(M).

Lowner, Pu, Accola, Blatter, Yu. Burago, Zalgaller, Gromov, Bavard, Calabi, M. Katz, Buser, Sarnak, Sabourau...

A manifold  $M^n$  is called essential if the image of its fundamental homology class in homology of  $K(\pi_1(M^n), 1)$  is non-trivial (under the homomorphism induced by the classifying map). Essential manifolds include non-simply connected surfaces, tori,  $RP^n$ .

#### Theorem

(*M.* Gromov) If  $M^n$  is essential, then there exists a non-contractible periodic geodesic of length  $\leq c(n) \operatorname{vol}(M^n)^{\frac{1}{n}}$ .

But, I. Babenko proved that this result holds only for essential manifolds.

1) The image of each edge is a geodesic;

2) For each vertex v the sum of unit tangent vectors at v to all edges adjacent to v is equal to 0.

1) The image of each edge is a geodesic;

2) For each vertex v the sum of unit tangent vectors at v to all edges adjacent to v is equal to 0.

This is a stationarity condition for the length functional (with respect to each 1-parametric group of diffeomorphisms of M).

1) The image of each edge is a geodesic;

2) For each vertex v the sum of unit tangent vectors at v to all edges adjacent to v is equal to 0.

This is a stationarity condition for the length functional (with respect to each 1-parametric group of diffeomorphisms of M). Geodesic nets are "homological" analogues of periodic geodesics.

1) The image of each edge is a geodesic;

2) For each vertex v the sum of unit tangent vectors at v to all edges adjacent to v is equal to 0.

This is a stationarity condition for the length functional (with respect to each 1-parametric group of diffeomorphisms of M). Geodesic nets are "homological" analogues of periodic geodesics.

#### Theorem

(A.N., R. Rotman) There exists (explicit) constants  $c_1(n)$ ,  $c_2(n)$  such that for each closed Riemannian manifold  $M^n$  the length of the shortest geodesic net on M does not exceed  $c_1(n)d$ . Also, it does not exceed  $c_2(n)vol(M^n)^{\frac{1}{n}}$ .

#### Theorem

(R. Rotman) The estimates in the previous theorem hold for the length of a shortest geodesic net that consists of at most N(n) geodesic loops based at the same point.

・ロト ・四ト ・ヨト ・ヨ

#### Problems about geodesic nets:

1. (M. Gromov) Is is true that for each closed Riemannian surface geodesic nets form a dense set?

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

## Problems about geodesic nets:

1. (M. Gromov) Is is true that for each closed Riemannian surface geodesic nets form a dense set?

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

2. Is it true that for each closed Riemannian manifold M there exists a geodesic net on M which is not composed of periodic geodesics?

#### Theorem

## (Y. Liokumovich, A. N., R. Rotman)

Let M be a Riemannian 2-sphere. Then there exist three simple periodic geodesics on M such that their lengths do not exceed, correspondingly, 5d, 10d and 20d, where d denotes the diameter of M.

- 日本 - 1 日本 - 日本 - 日本

#### Theorem

## (Y. Liokumovich, A. N., R. Rotman)

Let M be a Riemannian 2-sphere. Then there exist three simple periodic geodesics on M such that their lengths do not exceed, correspondingly, 5d, 10d and 20d, where d denotes the diameter of M.

A very general idea of the proof: The original proof by Lyusternik and Shnirelman uses three specific cycles in the space of nonparametrized simple closed curves on M.

#### Theorem

## (Y. Liokumovich, A. N., R. Rotman)

Let M be a Riemannian 2-sphere. Then there exist three simple periodic geodesics on M such that their lengths do not exceed, correspondingly, 5d, 10d and 20d, where d denotes the diameter of M.

A very general idea of the proof: The original proof by Lyusternik and Shnirelman uses three specific cycles in the space of nonparametrized simple closed curves on M. If M has a "nice" metric, then one can find homologous cycles that consist of "short" curves, and then the desired estimates follow from the existence proof.

#### Theorem

## (Y. Liokumovich, A. N., R. Rotman)

Let M be a Riemannian 2-sphere. Then there exist three simple periodic geodesics on M such that their lengths do not exceed, correspondingly, 5d, 10d and 20d, where d denotes the diameter of M.

A very general idea of the proof: The original proof by Lyusternik and Shnirelman uses three specific cycles in the space of nonparametrized simple closed curves on M.

If M has a "nice" metric, then one can find homologous cycles that consist of "short" curves, and then the desired estimates follow from the existence proof.

If M is not "nice", its "ruggedness" implies the existence of "short" simple closed geodesics that are local minima of the length functional.
Here "nice" means that M can be sliced into pairwise non-intersecting nonself-intersecting curves of length  $\leq const d$ connecting a pair of points. It turns out that one can use these curves to bound lengths of simple closed curves in some cycles representing each of the three homology classes in Lyusternik-Shnirelman proof.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <



Now one attempts to construct a slicing of M into nonself-intersecting curves of length  $\leq const \ d$  that connect a fixed pair of points. Our construction process can be blocked only by a simple periodic geodesic of index 0 and "small" length. Each time the extension process is blocked, we can continue in a different fashion until it is blocked again. We are done after the appearance of three "obstructing" simple periodic geodesics.

Note that, in general, one cannot slice a Riemannian 2-sphere into closed curves of length  $\leq const \ d$ . So, not all 2-spheres are "nice". For example:

## Theorem

(Y. Liokumovich) There is no contant C such that each Riemannian 2-sphere of diameter d can be divided into two parts of equal area by a (not necessarily connected) closed curve of length  $\leq Cd$ .

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

## Theorem

(Y. Liokumovich, A.N., R. Rotman) Let M be a Riemannian 2-sphere of diameter d and area A. Then it can be sliced into simple loops of length  $\leq 200d \max\{1, \ln \frac{\sqrt{A}}{d}\}$ . The simple loops intersect only at their common base point. This upper bound is optimal up to a constant factor.

## Theorem

(Y. Liokumovich, A.N., R. Rotman) Let M be a Riemannian 2-sphere of diameter d and area A. Then it can be sliced into simple loops of length  $\leq 200d \max\{1, \ln \frac{\sqrt{A}}{d}\}$ . The simple loops intersect only at their common base point. This upper bound is optimal up to a constant factor.

This theorem implies that three "original" LS simple periodic geodesics have length  $\leq 800d \max\{1, \ln \frac{\sqrt{A}}{d}\}$ .

## Theorem

(Y. Liokumovich, A.N., R. Rotman) Let M be a Riemannian 2-sphere of diameter d and area A. Then it can be sliced into simple loops of length  $\leq 200d \max\{1, \ln \frac{\sqrt{A}}{d}\}$ . The simple loops intersect only at their common base point. This upper bound is optimal up to a constant factor.

This theorem implies that three "original" LS simple periodic geodesics have length  $\leq 800d \max\{1, \ln \frac{\sqrt{A}}{d}\}$ . This theorem answers a question of S. Frankel and M. Katz which was a modification of an earlier question posed by M. Gromov. The strategy of the proof is to use cuts of several different types to reduce the problem to a similar "controlled" slicing problem for smaller and smaller subdiscs. The cuts come from the coarea formula, Besicovitch inequality and a version of Gromov's "attempted impossible extension" technique.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

# 3. Quantitative versions of Serre's theorem

## Theorem

(*R.* Rotman) Let  $M^n$  be a closed Riemannian manifold. For each  $p \in M^n$  there exists a geodesic loop based at p of length  $\leq 2nd$  (and even  $\leq 2qd$ , where  $q = \min\{i | \pi_i(M^n) \neq 0\}$ ).

# 3. Quantitative versions of Serre's theorem

# Theorem

(*R.* Rotman) Let  $M^n$  be a closed Riemannian manifold. For each  $p \in M^n$  there exists a geodesic loop based at p of length  $\leq 2nd$  (and even  $\leq 2qd$ , where  $q = \min\{i|\pi_i(M^n) \neq 0\}$ ).

## Theorem

(A.N., R. Rotman) Let p, q be any two points on a closed Riemannian manifold  $M^n$ . For every m there exists m distinct geodesics connecting p and q of length  $\leq 4m^2 nd$ .

# PROOF:

Curve-shortening process: It can be blocked only by many "short" geodesic loops.

Purpose: Given a curve  $\gamma$  connecting two points p and q we would like to shorten it by a path homotopy (=a homotopy that keeps p and q fixed).

Assumption: There are no geodesic loops based at p of length in the interval (I, I + 2d] for some I.

Conclusion: There is a path homotopy that shortens  $\gamma$  to the length  $\leq l + d$ .



æ

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Now consider the initial segment  $\gamma_0$  of  $\gamma$  of length  $l + d + \epsilon$ . Connect its endpoint with p by a minimizing geodesic  $\sigma$  (of length  $\leq d$ ). Insert  $\sigma$  traversed twice in the opposite directions inside  $\gamma$ .

Now consider the initial segment  $\gamma_0$  of  $\gamma$  of length  $l + d + \epsilon$ . Connect its endpoint with p by a minimizing geodesic  $\sigma$  (of length  $\leq d$ ). Insert  $\sigma$  traversed twice in the opposite directions inside  $\gamma$ . Shorten the loop  $\gamma_0 * \sigma$  to a geodesic loop  $\tau$  based at p by a path homotopy. The length of  $\tau \leq l$ . Curve  $\gamma$  shortens to  $\tau * \sigma^{-1} *$ the rest of  $\gamma$  that has length  $\leq \text{length}(\gamma) - \epsilon$ .

Now consider the initial segment  $\gamma_0$  of  $\gamma$  of length  $l + d + \epsilon$ . Connect its endpoint with p by a minimizing geodesic  $\sigma$  (of length  $\leq d$ ). Insert  $\sigma$  traversed twice in the opposite directions inside  $\gamma$ . Shorten the loop  $\gamma_0 * \sigma$  to a geodesic loop  $\tau$  based at p by a path homotopy. The length of  $\tau \leq l$ . Curve  $\gamma$  shortens to  $\tau * \sigma^{-1} *$ the rest of  $\gamma$  that has length  $\leq$  length $(\gamma) - \epsilon$ . Repeat the process.

Now consider the initial segment  $\gamma_0$  of  $\gamma$  of length  $l + d + \epsilon$ . Connect its endpoint with p by a minimizing geodesic  $\sigma$  (of length  $\leq d$ ). Insert  $\sigma$  traversed twice in the opposite directions inside  $\gamma$ . Shorten the loop  $\gamma_0 * \sigma$  to a geodesic loop  $\tau$  based at p by a path homotopy. The length of  $\tau \leq l$ . Curve  $\gamma$  shortens to  $\tau * \sigma^{-1} *$ the rest of  $\gamma$  that has length  $\leq$  length $(\gamma) - \epsilon$ . Repeat the process.

As *I* is arbitrary, one needs geodesic loops with length in intervals (0, 2d], (2d, 4d],... to block the curve shortening process.

The process is not continuous, but one can still construct a parametric version.

## Theorem

(A.N., R. Rotman) Let  $M^n$  be a closed Riemannian manifold,  $p \in M^n$ . Then either 1) there exist k geodesic loops of index 0 based at p with lengths is the index of (2 + 4 + 1) + 2 + 4

in the intervals (0, 2d], (2d, 4d], ..., (2(k-1)d, 2kd],

#### or

2) For each N any map of  $S^N$  into the space of based loops  $\Omega_p M^n$  can be homotoped to its subspace  $\Omega_p^L M^n$  that consists of loops of length  $\leq L = 4(k+2)(N+1)d$ .

Cohomology of the loop space of  $M^n$  with real coefficients: Using rational homotopy theory one concludes that there exists a cohomology class  $u \in H^{2l}(\Omega_p M^n, R)$  such that

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Cohomology of the loop space of  $M^n$  with real coefficients: Using rational homotopy theory one concludes that there exists a cohomology class  $u \in H^{2l}(\Omega_p M^n, R)$  such that 1) All cup powers of u are non-trivial;

Cohomology of the loop space of  $M^n$  with real coefficients: Using rational homotopy theory one concludes that there exists a cohomology class  $u \in H^{2l}(\Omega_p M^n, R)$  such that 1) All cup powers of u are non-trivial; 2)  $2l \leq 2n - 2$ ;

Cohomology of the loop space of  $M^n$  with real coefficients: Using rational homotopy theory one concludes that there exists a cohomology class  $u \in H^{2l}(\Omega_p M^n, R)$  such that 1) All cup powers of u are non-trivial; 2)  $2l \leq 2n - 2$ ; 3) u is "dual" to a spherical homology class h; cup powers of u are dual to Pontryagin powers of h. In simpler words,  $u^k$  "corresponds" to a cocycle formed by loops that are obtained as joins of k loops in (the image of) a 2l-sphere in  $\Omega_p M^n$  that corresponds to h.

Cohomology of the loop space of  $M^n$  with real coefficients: Using rational homotopy theory one concludes that there exists a cohomology class  $u \in H^{2l}(\Omega_p M^n, R)$  such that 1) All cup powers of u are non-trivial; 2)  $2l \leq 2n - 2$ ; 3) u is "dual" to a spherical homology class h; cup powers of u are dual to Pontryagin powers of h. In simpler words,  $u^k$  "corresponds" to a cocycle formed by loops that are obtained as joins of k loops in (the image of) a 2l-sphere in  $\Omega_p M^n$  that corresponds to h. The last theorem means that in the absence of many short geodesic loops of index 0 h can be "moved" to a subspace of the loop space formed by "short" loops.

The proof of Serre's theorem given by Albert Schwartz imples that the length of *k*th geodesic between *p* and *q* does not exceed  $c(M^n)k$ , where  $c(M^n)$  depends on the Riemannian metric on  $M^n$  in an unknown way.

Problem: Is it true that the length of the *k*th geodesic does not exceed c(n)kd, where c(n) depends only on *n*?

The proof of Serre's theorem given by Albert Schwartz imples that the length of *k*th geodesic between *p* and *q* does not exceed  $c(M^n)k$ , where  $c(M^n)$  depends on the Riemannian metric on  $M^n$  in an unknown way.

Problem: Is it true that the length of the *k*th geodesic does not exceed c(n)kd, where c(n) depends only on *n*?

## Theorem

(A.N., R. Rotman) If n = 2 then the length of the kth geodesic between p and q does not exceed 22kd.

Problem. Is there an upper bound for the length of the first k geodesics between p and q of the form c(k)d (that is, there is no dependence on n)?.

# 4. Quantiative versions of Almgren-Pitts theorem.

**Definition:** Let M be a Riemannian manifold such that  $H_1(M)$  is trivial. For each x > 0 the first homological filling function of M is defined as the infimum of y such that each closed curve of length  $\leq x$  can be represented as the boundary of a singular Lipschitz chain  $c = \sum_i a_i \sigma_i$  such that the area $(c) = \sum_i |a_i| \operatorname{area}(\sigma_i) \leq y$ .

# 4. Quantiative versions of Almgren-Pitts theorem.

**Definition:** Let M be a Riemannian manifold such that  $H_1(M)$  is trivial. For each x > 0 the first homological filling function of M is defined as the infimum of y such that each closed curve of length  $\leq x$  can be represented as the boundary of a singular Lipschitz chain  $c = \sum_i a_i \sigma_i$  such that the area $(c) = \sum_i |a_i| \operatorname{area}(\sigma_i) \leq y$ .

## Theorem

(A.N., R. Rotman) Let M be a Riemannian homology 3-sphere (e.g.  $S^3$ ). The smallest area of an embedded minimal surface in M does not exceed (i)  $6F_1(2d)$ ; (ii)  $12F_1(3300 \text{ vol}(M)^{\frac{1}{3}})$ .

One can generalize this theorem for higher dimensions and codimensions. On gets the same regularity of stationary varifolds as in known existence theorems.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

One can generalize this theorem for higher dimensions and codimensions. On gets the same regularity of stationary varifolds as in known existence theorems. To get an upper bound for the smallest mass of a stationary *k*-varifold one needs to assume vanishing of the first (k - 1) homology groups of *M*, and to use the corresponding (k - 1) homological filling functions as well as either the diameter or the volume of *M*.

One can generalize this theorem for higher dimensions and codimensions. On gets the same regularity of stationary varifolds as in known existence theorems. To get an upper bound for the smallest mass of a stationary *k*-varifold one needs to assume vanishing of the first (k - 1) homology groups of *M*, and to use the corresponding (k - 1) homological filling functions as well as either the diameter or the volume of *M*.

Problem. Is it true that each closed Riemannian 3-dimensional manifold of volume 1 contains a smooth embedded minimal surface of area  $\leq 10^{10}$  ?

(日) (同) (三) (三) (三) (○) (○)

(P. Glynn-Adey, Y. Liokumovich): A closed Riemannian manifold  $M^n$  of dimension  $n \in \{3, 4, 5, 6, 7\}$  satisfying  $Ric \ge -(n-1)a^2$  for  $a \ge 0$  contains a closed smooth embedded minimal hypersurface  $\Sigma$  of volume  $\le C(n) \max\{1, a \text{ vol}(M^n)^{\frac{1}{n}}\} \text{vol}(M^n)^{\frac{n-1}{n}}$ .

・ロト ・四ト ・ヨト ・ヨト ・ヨ

(P. Glynn-Adey, Y. Liokumovich): A closed Riemannian manifold  $M^n$  of dimension  $n \in \{3, 4, 5, 6, 7\}$  satisfying  $Ric \ge -(n-1)a^2$  for  $a \ge 0$  contains a closed smooth embedded minimal hypersurface  $\Sigma$  of volume  $\le C(n) \max\{1, a \ vol(M^n)^{\frac{1}{n}}\} vol(M^n)^{\frac{n-1}{n}}$ .

Their upper bound is for the (n-1)-width of M and holds for all n. It is a corollary of a stronger upper bound for the (n-1)-width that involves n,  $vol(M^n)$  and the "minimal conformal volume" of  $M^n$ , which is a scale-invariant conformal invariant.

(P. Glynn-Adey, Y. Liokumovich): A closed Riemannian manifold  $M^n$  of dimension  $n \in \{3, 4, 5, 6, 7\}$  satisfying  $Ric \ge -(n-1)a^2$  for  $a \ge 0$  contains a closed smooth embedded minimal hypersurface  $\Sigma$  of volume  $\le C(n) \max\{1, a \text{ vol}(M^n)^{\frac{1}{n}}\} \text{vol}(M^n)^{\frac{n-1}{n}}$ .

Their upper bound is for the (n-1)-width of M and holds for all n. It is a corollary of a stronger upper bound for the (n-1)-width that involves n,  $vol(M^n)$  and the "minimal conformal volume" of  $M^n$ , which is a scale-invariant conformal invariant. Note that there is no upper bound on the (n-1)-width of M in terms of vol(M), if n > 2 (Larry Guth; D. Burago and S. Ivanov).

(P. Glynn-Adey, Y. Liokumovich): A closed Riemannian manifold  $M^n$  of dimension  $n \in \{3, 4, 5, 6, 7\}$  satisfying  $Ric \ge -(n-1)a^2$  for  $a \ge 0$  contains a closed smooth embedded minimal hypersurface  $\Sigma$  of volume  $\le C(n) \max\{1, a \ vol(M^n)^{\frac{1}{n}}\} vol(M^n)^{\frac{n-1}{n}}$ .

Their upper bound is for the (n-1)-width of M and holds for all n. It is a corollary of a stronger upper bound for the (n-1)-width that involves n,  $vol(M^n)$  and the "minimal conformal volume" of  $M^n$ , which is a scale-invariant conformal invariant. Note that there is no upper bound on the (n-1)-width of M in terms of vol(M), if n > 2 (Larry Guth; D. Burago and S. Ivanov). So, one cannot hope for curvature-free estimates for (n-1)-widths.

Problem. Are there analogous results for higher codimensions?

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>
Problem. Are there analogous results for higher codimensions?

## Theorem

(P. Glynn-Adey, Y. Liokumovich); an effectice version of the existence theorem by Fernando Coda Marquees and André Neves Let  $M^n$  be a closed Riemannian manifold of dimension  $n \in \{3, 4, 5, 6, 7\}$  with positive Ricci curvature. Then for each k = 1, 2, ... it contains at least k distinct minimal hypersurfaces of volume  $\leq C(n) \frac{vol(M^n)}{\minvol_{n-1}(M^n)^{\frac{1}{n-1}}} k^{\frac{1}{n-1}}$ , where minvol<sub>n-1</sub>( $M^n$ ) denotes ther minimal volume of a non-trivial minimal hypersurface in  $M^n$ .

Problem. Are there analogous results for higher codimensions?

## Theorem

(P. Glynn-Adey, Y. Liokumovich); an effectice version of the existence theorem by Fernando Coda Marquees and André Neves Let  $M^n$  be a closed Riemannian manifold of dimension  $n \in \{3, 4, 5, 6, 7\}$  with positive Ricci curvature. Then for each k = 1, 2, ... it contains at least k distinct minimal hypersurfaces of volume  $\leq C(n) \frac{vol(M^n)}{\minvol_{n-1}(M^n)^{\frac{1}{n-1}}} k^{\frac{1}{n-1}}$ , where minvol<sub>n-1</sub>( $M^n$ ) denotes ther minimal volume of a non-trivial minimal hypersurface in  $M^n$ .

Question. Is it possible to get rid of  $minvol_{n-1}(M^n)$  in this estimate?

## General ideas behind proofs:

▲□▶ ▲□▶ ▲国▶ ▲国▶ 三国 - のへで

General ideas behind proofs: 1. The desired minimal object on a Riemannian manifold M comes from a known or unknown homology class h in a space X(M) of based loops, or free loops, or cycles.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

General ideas behind proofs: 1. The desired minimal object on a Riemannian manifold M comes from a known or unknown homology class h in a space X(M) of based loops, or free loops, or cycles. It would be helpful to represent h by a cycle made of "short" loops or cycles of a controlled volume. Then Morse theory yields the desired estimate. In many cases we can settle for any non-trivial homology class (maybe, of a prescribed dimension). More precisely, we want to represent h by a homology or homotopy class of M swept-out by "short" loops or "small" cycles.

General ideas behind proofs: 1. The desired minimal object on a Riemannian manifold M comes from a known or unknown homology class h in a space X(M) of based loops, or free loops, or cycles. It would be helpful to represent h by a cycle made of "short" loops or cycles of a controlled volume. Then Morse theory yields the desired estimate. In many cases we can settle for any non-trivial homology class (maybe, of a prescribed dimension). More precisely, we want to represent h by a homology or homotopy class of *M* swept-out by "short" loops or "small" cycles. 2. Assume that this class is represented by a map f of, say, a sphere  $S^m$  to M. We can attempt an (impossible) extension of f to a disc  $D^{m+1}$  triaingulated as a cone over  $S^m$ . Induction is done by induction with respect to skeleta.

General ideas behind proofs: 1. The desired minimal object on a Riemannian manifold M comes from a known or unknown homology class h in a space X(M) of based loops, or free loops, or cycles. It would be helpful to represent h by a cycle made of "short" loops or cycles of a controlled volume. Then Morse theory yields the desired estimate. In many cases we can settle for any non-trivial homology class (maybe, of a prescribed dimension). More precisely, we want to represent h by a homology or homotopy class of M swept-out by "short" loops or "small" cycles. 2. Assume that this class is represented by a map f of, say, a sphere  $S^m$  to M. We can attempt an (impossible) extension of fto a disc  $D^{m+1}$  triaingulated as a cone over  $S^m$ . Induction is done

by induction with respect to skeleta.

3. Each step is an extension in M, but we try to represent it as an extension in X(M) so that the image of the extension consists "small" objects in X(M). If an extension in X(M) is impossible, then there is a "small" extremal object in X(M) obstructing the extension process.

General ideas behind proofs: 1. The desired minimal object on a Riemannian manifold M comes from a known or unknown homology class h in a space X(M) of based loops, or free loops, or cycles. It would be helpful to represent h by a cycle made of "short" loops or cycles of a controlled volume. Then Morse theory yields the desired estimate. In many cases we can settle for any non-trivial homology class (maybe, of a prescribed dimension). More precisely, we want to represent h by a homology or homotopy class of M swept-out by "short" loops or "small" cycles. 2. Assume that this class is represented by a map f of, say, a sphere  $S^m$  to M. We can attempt an (impossible) extension of fto a disc  $D^{m+1}$  triaingulated as a cone over  $S^m$ . Induction is done

by induction with respect to skeleta.

3. Each step is an extension in M, but we try to represent it as an extension in X(M) so that the image of the extension consists "small" objects in X(M). If an extension in X(M) is impossible, then there is a "small" extremal object in X(M) obstructing the extension process.

4. If the extension process is unobstructed up to the dimension m, then the boundary of at least one of (m + 1)-cells of  $D^{m+1}$  represents a non-trivial cycle. Its boundary had been mapped into "small" objects in X(M), and its contractibility is obstructed by a "small" minimal object in X(M).

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

4. If the extension process is unobstructed up to the dimension m, then the boundary of at least one of (m + 1)-cells of  $D^{m+1}$  represents a non-trivial cycle. Its boundary had been mapped into "small" objects in X(M), and its contractibility is obstructed by a "small" minimal object in X(M).

5. Another useful "attempted impossible extension" (Gromov): Embed  $M = M^n$  into  $L^{\infty}(M)$  using Kuratowski embedding. Represent  $M^n$  as  $\partial W^{n+1}$ , where W is an  $c(n)vol^{\frac{1}{n}}(M^n)$ -neighborhood of  $M^n$  (Gromov's filling radius theorem). Triangulate  $W^{n+1}$  into small simplices, and attempt to extend the identity map  $M^n \longrightarrow M^n$  to a map of  $W^{n+1}$  into  $M^n$ . First, one sends all vertices to closest points of  $M^n$ , then 1-simplices to minimal geodesics, setting the scale for subsequent steps of the extension process as  $const(n)vol(M^n)^{\frac{1}{n}}$ . 6. Assume that one needs to establish upper bounds not just for one minimal object in M but for a finite or infinite family of minimal objects.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

6. Assume that one needs to establish upper bounds not just for one minimal object in M but for a finite or infinite family of minimal objects. If one has a sweep-out of a class of M by "small" loops or cycles, one typically gets the desired estimate not for just one minimal object but for all of them.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

6. Assume that one needs to establish upper bounds not just for one minimal object in M but for a finite or infinite family of minimal objects. If one has a sweep-out of a class of M by "small" loops or cycles, one typically gets the desired estimate not for just one minimal object but for all of them. On the other hand, the extension process can be obstructed by just one "small" minimal object. The idea is to start the extension process anew looking for maps into "bigger" objects in X(M). The idea is that either we are going to get "bigger" and "bigger" obstructing minimal objects, or we will get a desired "controlled" sweep-out.